Appendectomy Without Anesthesia? Ambulance in a Blink! Inside the Framework of Whom 'Tech Whales' Call Einstein of 2026

Sheridan, Wyoming Aug 29, 2026 (Issuewire.com**)** - A Wyoming-based engineering company, MAM-NEXUS TECHNOLOGIES L.L.C., is developing multidisciplinary engineering frameworks spanning biomedical robotics, autonomous systems, aviation energy recovery, and theoretical physics.

The company’s portfolio explores engineering approaches to complex mechanical and electromechanical challenges encountered in advanced robotics programs, including challenges associated with intraluminal robotics, autonomous mobility, and distributed robotic systems.

One of the company’s concepts is a transformable emergency ambulance pod designed to investigate whether adaptive structural morphology, closed-loop control systems, and gyroscopic suspension could improve mobility through severe traffic congestion during the “Golden Hour.” The underlying engineering architecture also explores “dual-stage anchor-and-actuation systems” for capsule robotics and their potential implementation within the MAM-7 medical robotics research framework and the MATP transformable ambulance concept.

The portfolio brings together engineering algorithms, mathematical models, simulation frameworks, and research concepts developed across several technological sectors.

The Badge of International Recognition and Documentation for the Portfolio:

• Silicon Valley Trust (Silicon Valley): The project reached advanced stages and the finalist waitlist in the Founder Institute Silicon Valley incubator (California), representing a documented milestone in the project's entrepreneurial development.

• European Government Incubation: The project has been presented to and engaged with innovation organizations in Portugal, including Build Up Labs, UPTEC (Science and Technology Park of the University of Porto), and Instituto Pedro Nunes (IPN), as part of its international incubation and innovation-development activities.

• Academic Verdict: The engineering background and research concepts associated with the portfolio have been presented within academic contexts involving professors and faculty members associated with the Universidad Politécnica de Madrid (UPM) (Spain) and the University of Auckland for Robotics and Automation (New Zealand). Corresponding research materials and engineering frameworks are documented through the publications and digital records referenced below.

One Simulation Engine.. and Four Sectors Whose Balances We Flip:

Through the adaptation of kinetic dynamics equations and predictive fluid dynamics simulation, the current technology architecture includes research and engineering frameworks documented through active International Digital Object Identifiers.

• Biomedical & Robotics (MAM-7 & MAM-SWARM): A proposed 7-step hybrid protocol investigating the engineering feasibility of root-level appendectomy without general anesthesia or systemic sedation, with the concept envisioning a fully conscious patient through colonic endoscopy robotics. The framework is presented as an engineering and research concept for potential future medical applications and regulatory evaluation, including exploration of a potential FDA De Novo pathway (DOIs): https://doi.org/10.5281/zenodo.20511480 and https://doi.org/10.5281/zenodo.20576180

• Smart Cities & Autonomous Systems (MATP System): An engineering concept for a transformable ambulance pod utilizing closed-loop control systems and gyroscopic suspension to dynamically alter its shape and structural morphology, with the objective of investigating whether such a configuration could improve mobility through severe traffic congestion during the "Golden Hour" (DOI): https://doi.org/10.5281/zenodo.21212780

• Aviation & Clean Energy (Slipstream UAV Charging): An engineering research concept exploring the mechanical recovery of kinetic energy associated with aircraft exhaust streams through dynamically stabilized and synchronized escort drone fleets, with the objective of generating electrical energy and potentially reducing the energy and fuel burden associated with conventional aviation systems.

• Theoretical Physics (The Photonic-Fluid Framework – Alqadi Theory): A proposed theoretical framework exploring structural mechanics of matter from the sub-atomic scale to the cosmic scale through the vacuum-vortex model and cosmic matter dynamics. The framework presents an alternative conceptual interpretation of fundamental physical phenomena and seeks to simplify complex physical concepts for students and beginners (DOI): https://doi.org/10.5281/zenodo.21398237

Global Strategic Execution:

The portfolio brings together research directions addressing intra-body biomedical robotics through MAM-7 endoscopy, autonomous driving vision challenges through the Active Sensing Matrix, and drone communication resilience through the Decentralized Tethered Swarm. The unified physics-layer

framework connects these areas with a broader engineering approach spanning biomedical robotics, autonomous systems, aviation, and theoretical physics.

The broader research direction investigates whether fundamental engineering principles can provide new approaches to complex technological bottlenecks while also connecting theoretical concepts taught in schools and universities with practical engineering models and applications.

Media Contact & Verification Domains:

• Inventor Engineer: Inv. Eng. Mahmoud Alqadi

• Professional Portal: https://www.linkedin.com/in/mahmoud-a-152aa7103

• Corporate Framework: MAM-NEXUS TECHNOLOGIES L.L.C. (Wyoming, USA)

EDITORIAL NOTE: The medical, scientific, engineering, and institutional statements presented in this press release describe research projects, proposed engineering frameworks, documented development activities, and professional or academic engagements. The referenced DOIs provide documentation of the corresponding published materials. Nothing herein should be interpreted as a claim of completed clinical validation, regulatory approval, or institutional endorsement unless expressly identified and independently verifiable.

Media Contact

MAM-NEXUS TECHNOLOGIES L.L.C.

*********@mamnexus.com

+6285215403194

Https://www.mamnexus.com

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